

Outline

- 1 Motivation and Scope of Our Work
- 2 Infeasibility Certificates
- 3 Efficient Algorithm to Create Datasets
- 4 Balanced Datasets for PGLib-OPF cases
- 5 Conclusions

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Motivation

- Machine learning including neural networks have been applied to a range of power system applications since decades ([Wehenkel, Springer, 2012](#))
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⇒ Recent advances in deep learning have sparked renewed interest
- Machine learning for power system security assessment
 - **static** security criteria such as N-1 security criterion and operational constraints
 - **dynamic** stability criteria such as small-signal or transient stability
- Application example: Convolutional neural networks to predict
 - N-1 security ([Du et al., TPWRS, 2019](#))
 - N-1 security + small signal stability ([Arteaga et al., PowerTech, 2019](#))
⇒ **Two orders** of magnitude faster than conventional approaches

Scope of Our Work

Performance of machine learning **highly** depends on dataset quality

- Historical data: limited information of **abnormal** situations
- High problem **dimensionality** (number of control variables)

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Performance of machine learning **highly** depends on dataset quality

- Historical data: limited information of **abnormal** situations
- High problem **dimensionality** (number of control variables)

Requires **balanced** datasets of secure and not secure operating points with **detailed** security boundary description

- **Computationally hard** due to large **input dimensionality**
- E.g. creating dataset for 162-bus system for 1 MW discretization and one loading level requires to evaluate $\approx 10^{29}$ operating points

Scope of Our Work

- ① **Importance sampling**: Bias sampling towards region of interest
([Krishnan et al., TPWRS, 2011](#))
⇒ Input space in power systems is largely unbalanced
- ② **Composite approaches** or **vine copulas** to enrich historical data
([Sun et al., PSCC, 2016](#)), ([Konstantelos et al., TPWRS, 2019](#))
⇒ Highly dependent on data quality

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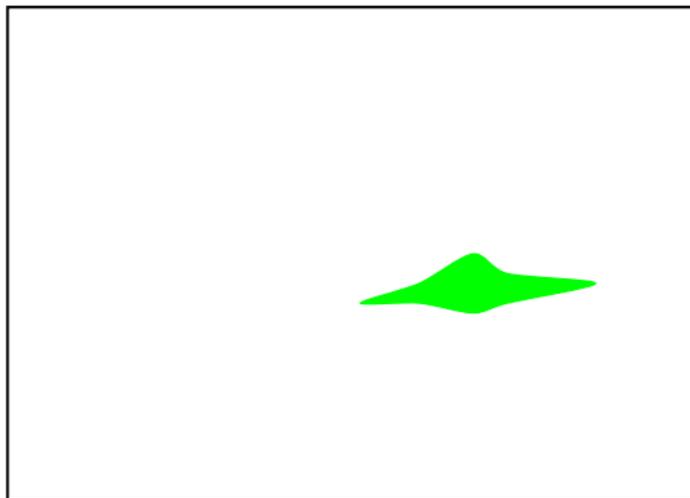
Our approach is **modular** and **parallelizable**:

- Uses **infeasibility certificates** to classify large parts of input space **a-priori** as **not secure**
- Obtains a detailed **boundary** description
- Creates **balanced** datasets and can leverage historical data

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Infeasibility Certificates

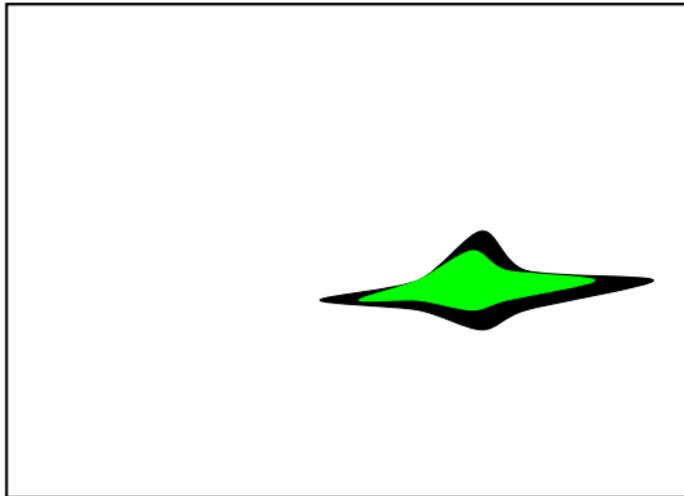


□ Input space \mathcal{D}
 ★ Secure space

- Goal: For a defined input space \mathcal{D} of dimension d obtain a balanced dataset characterizing the boundary of the secure space

- E.g. for operating point $\mathbf{x} = \begin{bmatrix} \mathbf{P}_G \\ \mathbf{V}_G \end{bmatrix} \in \mathcal{R}^d$, $\mathcal{D} : \begin{bmatrix} \mathbf{P}_G^{\min} \\ \mathbf{V}_G^{\min} \end{bmatrix} \leq \mathbf{x} \leq \begin{bmatrix} \mathbf{P}_G^{\max} \\ \mathbf{V}_G^{\max} \end{bmatrix}$

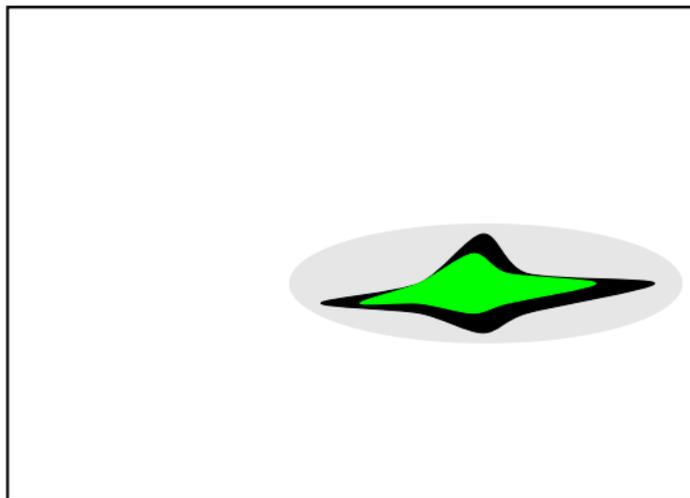
Infeasibility Certificates



- Input space \mathcal{D}
- ★ Secure space
- ★ AC-feasible space

- Pre-requisite for assessment of **dynamic** stability criteria is feasibility to **static** security criteria such as N-1 security and operational constraints
- Static security criteria are described in the AC optimal power flow (**AC-OPF**) problem

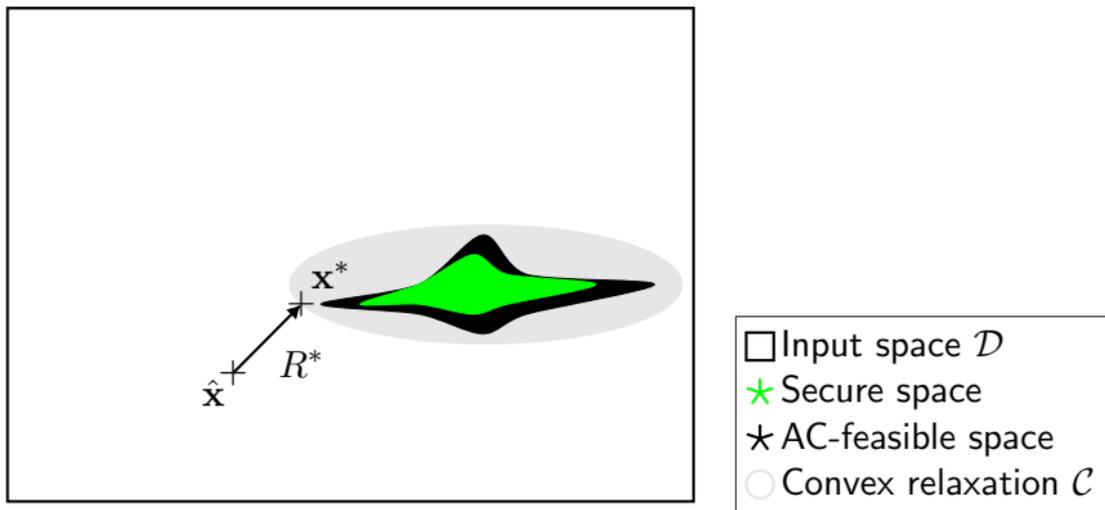
Infeasibility Certificates



- Input space \mathcal{D}
- Secure space
- AC-feasible space
- Convex relaxation \mathcal{C}

- **Convex relaxations** of AC-OPF can provide **infeasibility** certificate

Infeasibility Certificates

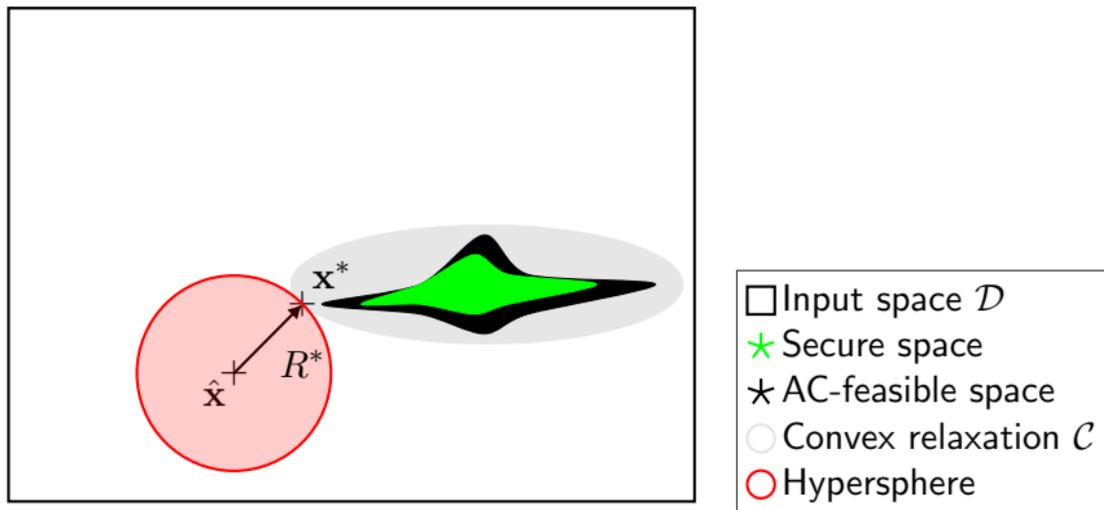


- For **infeasible** operating point $\hat{\mathbf{x}}$ compute closest dispatch \mathbf{x}^* **feasible** to convex relaxation of AC-OPF:

$$\min_{\mathbf{x}^*} \|\mathbf{x}^* - \hat{\mathbf{x}}\|_2$$

s.t. \mathbf{x}^* feasible to convex relaxation of AC-OPF

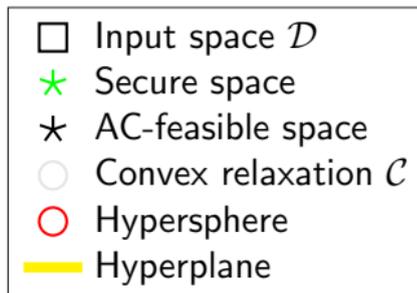
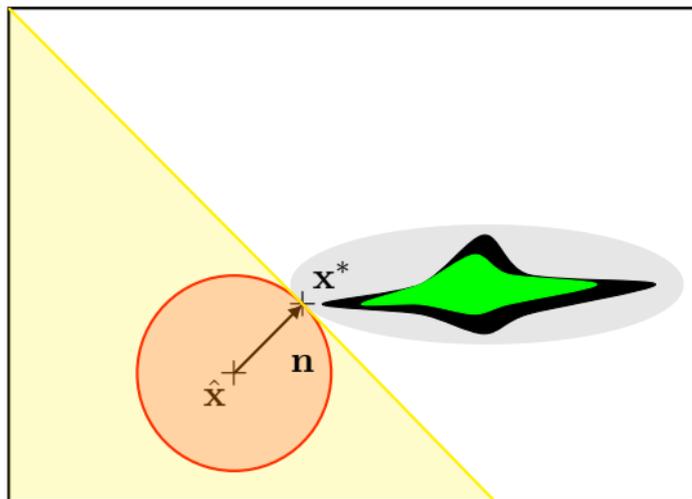
Infeasibility Certificates



- (Molzahn, TPWRS, 2018) proposed **hyperspheres** with radius R^* as infeasibility certificates:

$$\forall \mathbf{x} : |\hat{\mathbf{x}} - \mathbf{x}|_2 < R^* \Rightarrow \mathbf{x} \notin \mathcal{C}$$

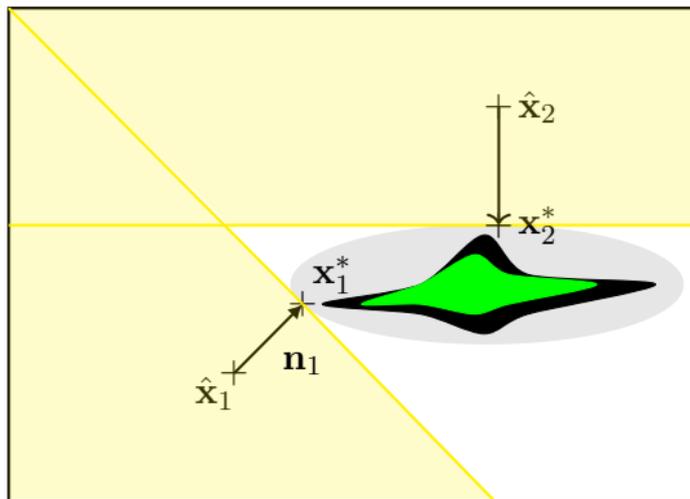
Infeasibility Certificates



- We propose to use separating **hyperplanes** as infeasibility certificates:

$$\forall \mathbf{x} : \mathbf{n}^T (\mathbf{x} - \mathbf{x}^*) < 0 \Rightarrow \mathbf{x} \notin \mathcal{C}$$

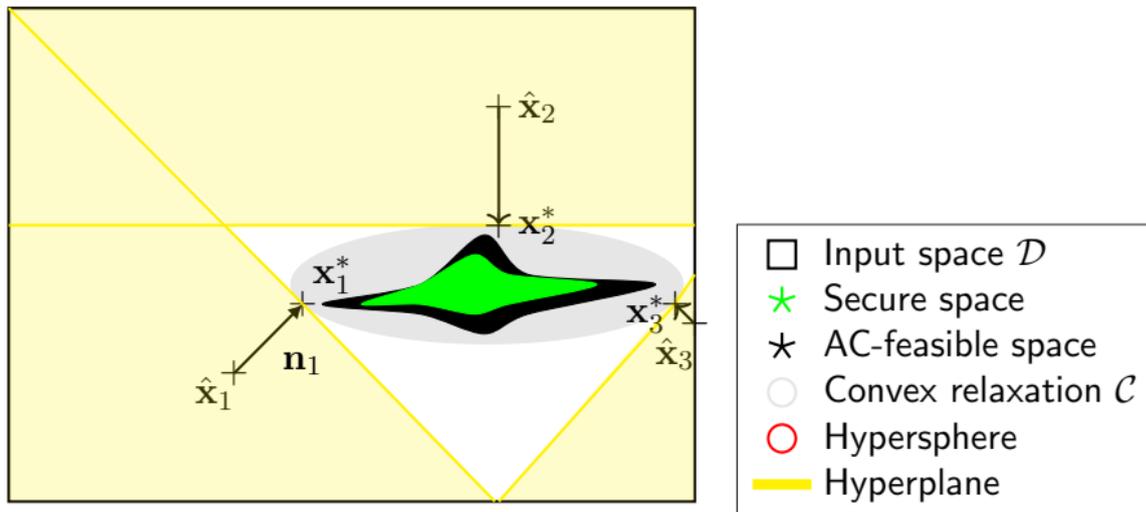
Infeasibility Certificates



- Input space \mathcal{D}
- ★ Secure space
- ★ AC-feasible space
- Convex relaxation \mathcal{C}
- Hypersphere
- Hyperplane

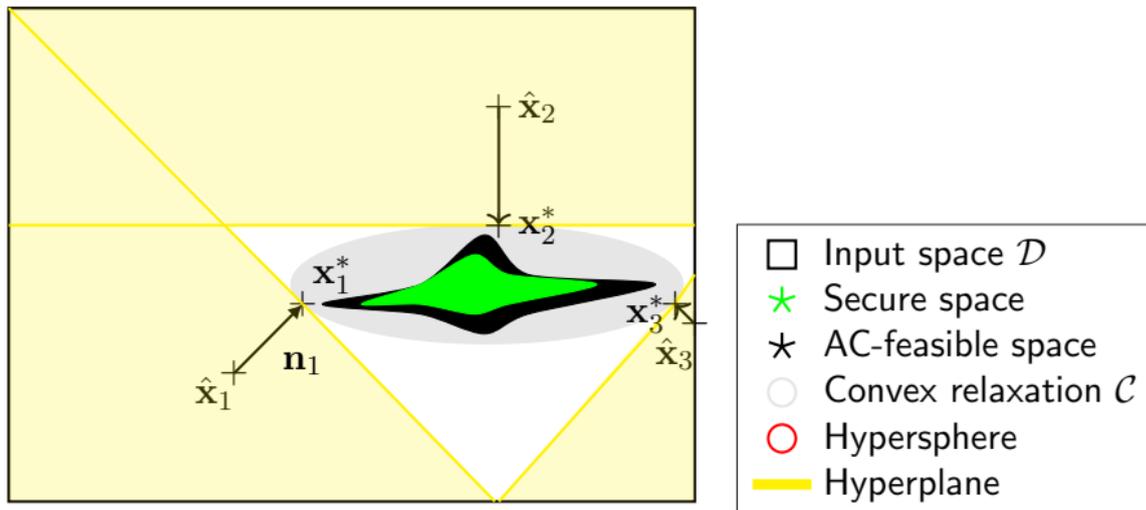
- Observation: Multiple hyperplanes form **convex polyhedron**

Infeasibility Certificates



- Observation: Multiple hyperplanes form **convex polyhedron**

Infeasibility Certificates



- Benefits of hyperplanes:

- ① Larger parts of input space classified as infeasible
- ② Efficient methods available to sample from within a convex polyhedron

Algorithm to Minimize Unclassified Input Space

Goal: minimize volume of **convex polyhedron** using N_1 iterations

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Goal: minimize volume of **convex polyhedron** using N_1 iterations

1 Set iteration count $k \leftarrow 0$. Initialize unclassified input space as

$\mathbf{A}^{(0)} \mathbf{x} \leq \mathbf{b}^{(0)}$ with:

$$\mathbf{A}^{(0)} := [\mathbf{I}^{|x| \times |x|} \quad -\mathbf{I}^{|x| \times |x|}]^T$$

$$\mathbf{b}^{(0)} := [(\mathbf{x}^{\max})^T \quad (\mathbf{x}^{\min})^T]^T$$

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- 2 If $k \leq N_1$ continue, otherwise terminate. Increase $k \leftarrow k + 1$. Draw random $\mathbf{x}^{(k)}$ from inside $\mathbf{A}^{(k)} \mathbf{x} \leq \mathbf{b}^{(k)}$. Compute closest feasible sample with $\hat{\mathbf{x}} := \mathbf{x}^{(k)}$ and obtain \mathbf{x}^* and R^* .

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Draw random $\mathbf{x}^{(k)}$ from inside $\mathbf{A}^{(k)} \mathbf{x} \leq \mathbf{b}^{(k)}$. Compute closest feasible sample with $\hat{\mathbf{x}} := \mathbf{x}^{(k)}$ and obtain \mathbf{x}^* and R^* .

- ③ If $R^* > 0$ reduce unclassified region by adding hyperplane.

$$\mathbf{A}^{(k+1)} = [(\mathbf{A}^{(k)})^T \quad \mathbf{n}^T]^T$$

$$\mathbf{b}^{(k+1)} = [(\mathbf{b}^{(k)})^T \quad \mathbf{n}^T \mathbf{x}^*]^T$$

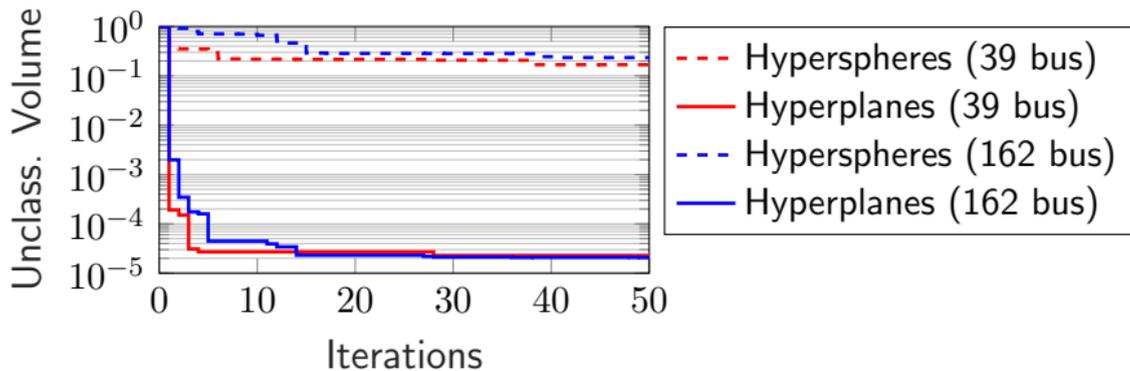
Return to step 2.

Comparison of Infeasibility Certificates

- Reference normalized volume is 1
- Use *voesti* ([Emiris et al., ACM TOMS, 2018](#)) to approximate the volume of a convex polyhedron
- Rejection sampling for the volume of hyperspheres

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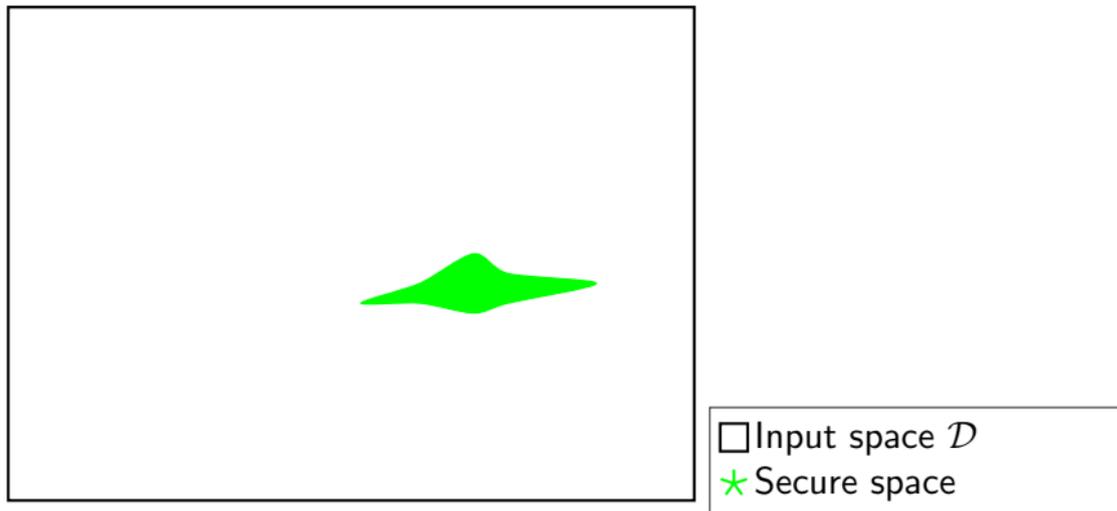


- Volume reduction from 1 to 10^{-5} implies that in expectation at least 10^5 random samples are required to identify 1 potential feasible sample.

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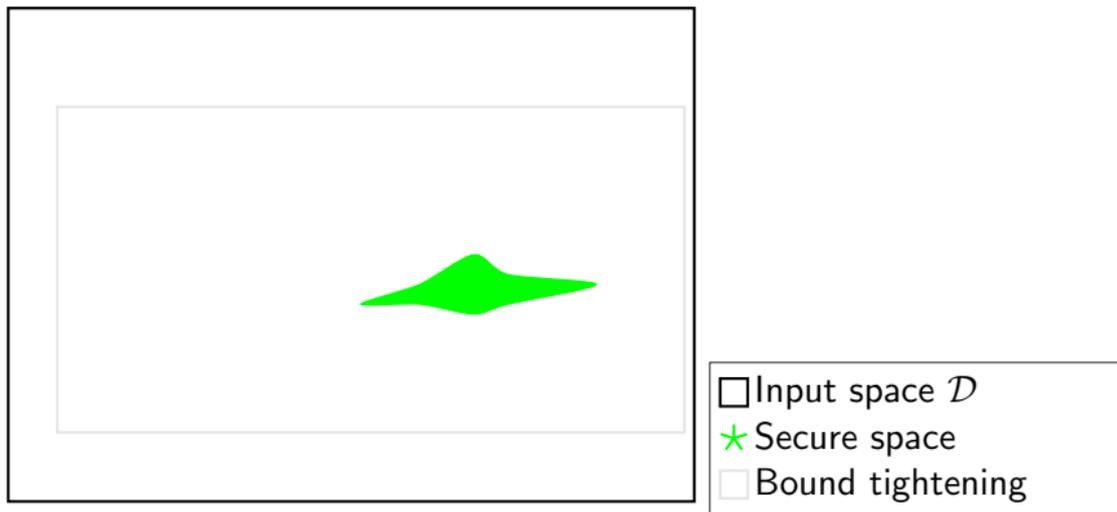
- ① Motivation and Scope of Our Work
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Efficient Algorithm to Create Datasets



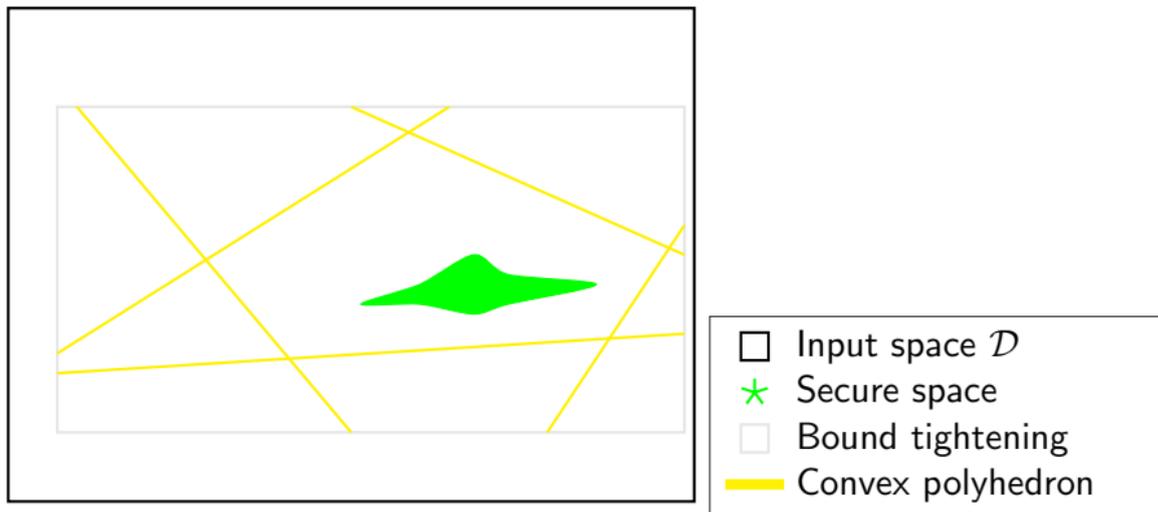
- ① Goal: Computationally efficient creation of balanced datasets of secure and insecure operating points with a detailed boundary description

Efficient Algorithm to Create Datasets



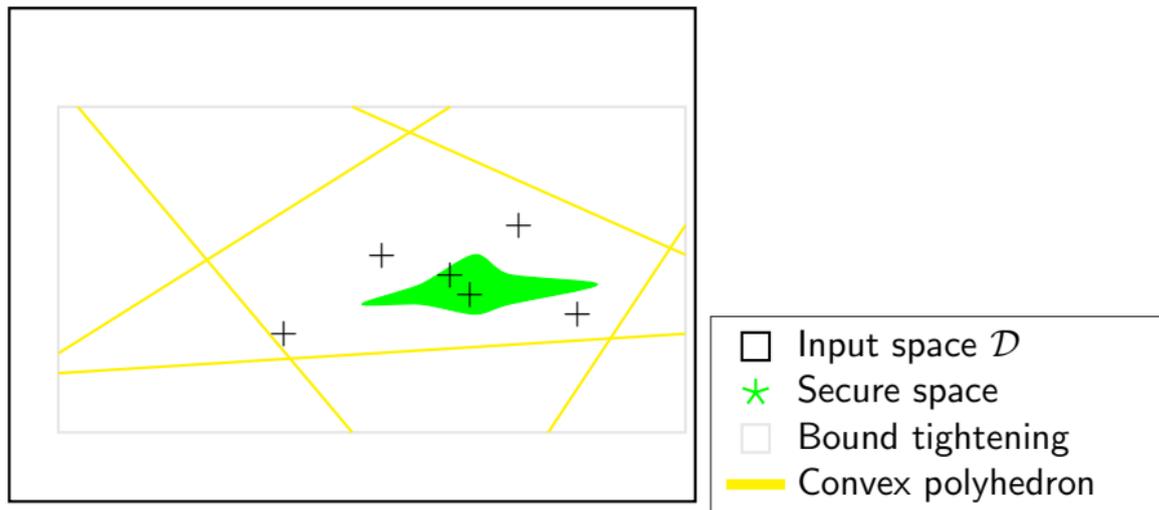
- 1 **Bound tightening** for AC-OPF problem
- 2 Direct tightening of input bounds by maximizing and minimizing \mathbf{x} subject to constraints of convex relaxations of AC-OPF
 \Rightarrow reduce unclassified volume to V^{BT}

Efficient Algorithm to Create Datasets



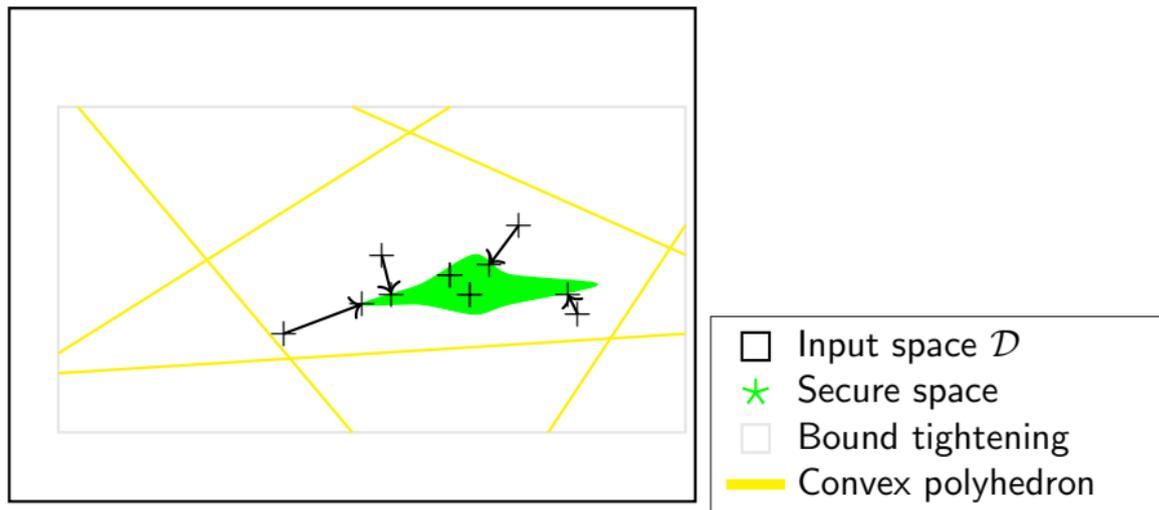
- ③ Run algorithm to minimize unclassified input space for N_1 steps
 \Rightarrow convex polyhedron $\mathbf{Ax} \leq \mathbf{b}$ with unclassified volume V^{HP}

Efficient Algorithm to Create Datasets



- 4 Draw and classify N_2 samples from within convex polyhedron

Efficient Algorithm to Create Datasets

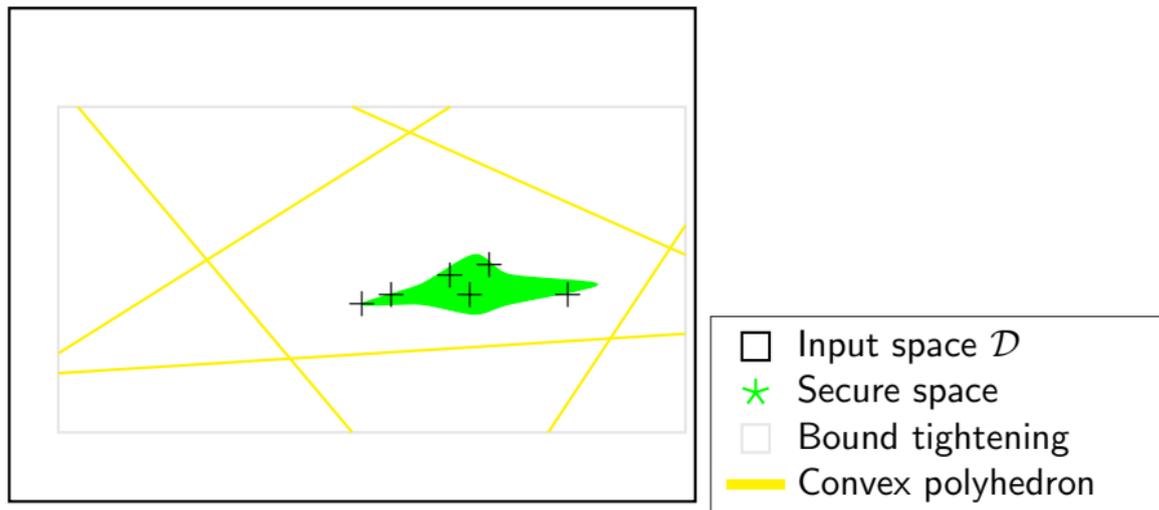


5 Obtain detailed boundary identification. For each infeasible sample x identify **closest** secure operation point.

- Static Security: Solve OPF minimizing distance to feasible solution
- Dynamic Security: Directed walks using sensitivity measures

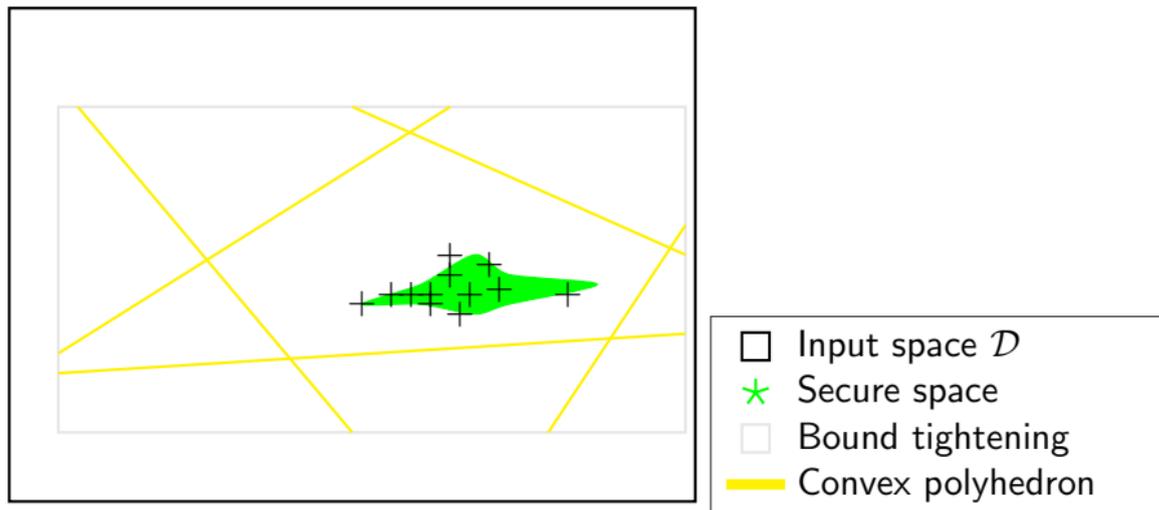
For dynamic security more details in our paper: Thams, F., Venzke, A., Eriksson, R. and Chatzivasileiadis, S., 2019. Efficient database generation for data-driven security assessment of power systems. IEEE Transactions on Power Systems. PSCC 2020, Andreas Venzke 30/6/2020

Efficient Algorithm to Create Datasets



- ⑥ Fit multi-variate Gaussian distribution to obtained secure samples (and if available historical data). Bias sampling towards inside the secure space by multiplying covariance matrix with $s_{\text{red}} \leq 1$.

Efficient Algorithm to Create Datasets



⑦ Draw and classify N_3 samples from fitted distribution.

⇒ Algorithm **parallelizable** and **modular**

⇒ Can include e.g. importance sampling or vine-copulas as well

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Simulation Setup

- We use the **QC relaxation** and existing bound tightening techniques:
 - Analytical bound tightening ([Shchetinin et al., TPWRS, 2019](#))
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- Security criteria:
 - ① Operational constraints (AC-OPF)
 - ② N-1 security + uncertainty in generation and loading (N-1 SC-AC-OPF)
- We evaluate ① on 13 PGLib-OPF test cases up to 500 buses and input dimensionality $|\mathbf{x}| = d$ of 125
- We evaluate ② on 39- and 162 bus test cases considering 5 line outages, 3 uncertain loads, and 3 uncertain renewable generators

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- We evaluate ② on 39- and 162 bus test cases considering 5 line outages, 3 uncertain loads, and 3 uncertain renewable generators
- Sampling sizes:
 - $N_1 = 10^3$ potential hyperplanes
 - $N_2 = 10^4$ samples from convex polyhedron
 - $N_3 = 10^5$ samples from multivariate Gaussian distribution ($s_{\text{red}} = 0.25$)

Unclassified Input Volumes for PGLib-OPF Cases

case	Dim. d	V^{BT}	$ HP $	V^{HP}
(1) Operational constraints				
<i>case30_ieee</i>	7	6.2e-03		
<i>case73_ieee_rts</i>	62	1.0e+00		
<i>case300_ieee</i>	125	1.0e-12		
Median 13 cases	23	8.6e-02		
(2) N-1 security and uncertainty				
<i>case39_epri</i>	25	2.6e-01		
<i>case162_ieee_dtc</i>	29	2.2e-04		

- **Bound tightening** allows to a-priori reduce the unclassified input space
- The reduction is **test-case dependent**

Unclassified Input Volumes for PGLib-OPF Cases

case	Dim. d	V^{BT}	$ HP $	V^{HP}
(1) Operational constraints				
<i>case30_ieee</i>	7	6.2e-03	61	8.8e-06
<i>case73_ieee_rts</i>	62	1.0e+00	608	6.1e-16
<i>case300_ieee</i>	125	1.0e-12	1000	3.4e-40
Median 13 cases	23	8.6e-02	271	7.0e-08
(2) N-1 security and uncertainty				
<i>case39_epri</i>	25	2.6e-01	271	2.0e-05
<i>case162_ieee_dtc</i>	29	2.2e-04	394	6.0e-10

- Using the algorithm based on hyperplanes allows to **significantly reduce** the unclassified input space for **all** 15 test cases
- For some test cases, larger number N_1 could lead to further reductions

Created Datasets for PGLib-OPF Cases

Share of secure samples (%)			
Power system case	Boundary Identification $N_2 = 10^4$	Inside (MVG D) $N_3 = 10^5$	Overall Secure
(1) Operational constraints			
<i>case30_ieee</i>			75.0%
<i>case73_ieee_rts</i>			63.9%
<i>case300_ieee</i>			50.0%
Average all 13 cases			59.7%
(2) N-1 security and uncertainty			
<i>case39_epri</i>			58.2%
<i>case162_ieee_dtc</i>			50.0%

- **Directly** sampling from convex polyhedron identifies secure samples

Created Datasets for PGLib-OPF Cases

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<i>case73_ieee_rts</i>	63.9%	51.1%	
<i>case300_ieee</i>	50.0%	32.6%	
Average all 13 cases	59.7%	44.2%	
(2) N-1 security and uncertainty			
<i>case39_epri</i>	58.2%	78.2%	
<i>case162_ieee_dtc</i>	50.0%	17.9%	

- Sampling from fitted multi-variate Gaussian distribution

Created Datasets for PGLib-OPF Cases

Share of secure samples (%)			
Power system case	Boundary Identification $N_2 = 10^4$	Inside (MVG D) $N_3 = 10^5$	Overall Secure
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<i>case73_ieee_rts</i>	63.9%	51.1%	52.7%
<i>case300_ieee</i>	50.0%	32.6%	34.7%
Average all 13 cases	59.7%	44.2%	46.5%
(2) N-1 security and uncertainty			
<i>case39_epri</i>	58.2%	78.2%	75.2%
<i>case162_ieee_dtc</i>	50.0%	17.9%	23.2%

- We obtain **balanced** datasets for a range of test cases

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Conclusions

- Proposed **infeasibility** certificates based on **hyperplanes**
- Introduced algorithm to **a-priori** minimize unclassified input space
⇒ Reduced volumes ranging from 10^{-2} up to 10^{-40} .
- **Modular** and parallelizable algorithm created **balanced** datasets with detailed security **boundary description**
- We plan to soon release an **open-source implementation + datasets!**

Open Questions

Thank you for your attention!

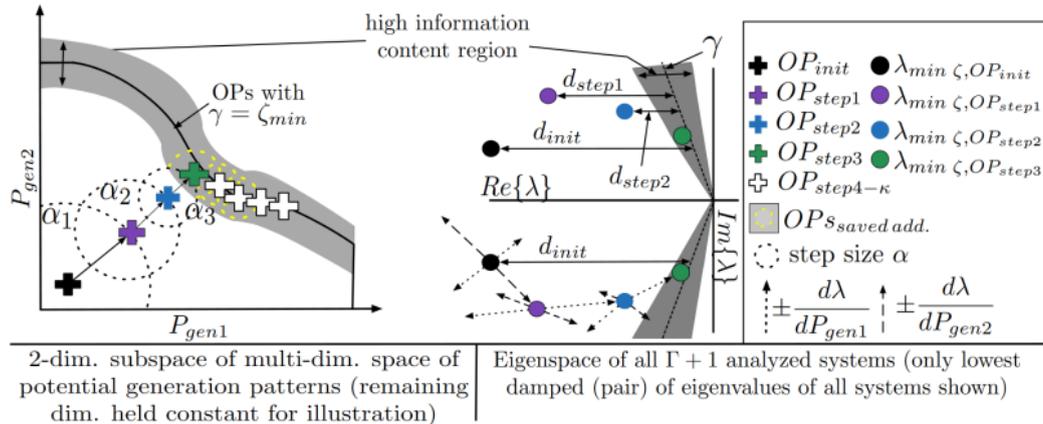
Do you have any questions?



source: www.DTU.dk

Appendix

Directed walks for dynamic security criteria



- Security Criteria: N-1 security + small-signal stability
- Illustration of the Directed Walk (DW) through a two dimensional space using varying step sizes, α_i , following the steepest descent of distance, d .
- **For dynamic security more details in our paper:** Thams, F., Venzke, A., Eriksson, R. and Chatzivasileiadis, S., 2019. Efficient database generation for data-driven security assessment of power systems. IEEE Transactions on Power Systems.

Full results – Unclassified input volumes

case	$ x $	V^{BT}	$ HP $	V^{HP}	$\frac{-\log_{10}(V)}{ x }$
AC-OPF without N-1 security and without uncertainty					
<i>case3_lmbd</i>	4	6.3e-02	28	3.3e-02	37.0%
<i>case5_pjm</i>	7	1.0e+00	99	6.9e-03	30.9%
<i>case14_ieee</i>	6	2.4e-01	54	6.9e-04	52.7%
<i>case24_ieee_rts</i>	20	9.2e-01	184	2.3e-06	28.2%
<i>case30_ieee</i>	7	6.2e-03	61	8.8e-06	72.2%
<i>case39_epri</i>	19	9.9e-02	203	7.0e-08	37.7%
<i>case57_ieee</i>	10	3.8e-02	231	4.9e-06	53.1%
<i>case73_ieee_rts</i>	62	1.0e+00	608	6.1e-16	24.5%
<i>case118_ieee</i>	72	1.7e-02	1000	1.6e-17	23.3%
<i>case162_ieee_dtc</i>	23	6.1e-04	371	1.5e-11	47.1%
<i>case200_tamu</i>	69	9.3e-01	1000	6.0e-11	14.8%
<i>case300_ieee</i>	125	1.0e-12	1000	3.4e-40	31.6%
<i>case500_tamu</i>	111	8.6e-02	1000	5.4e-26	22.8%

Full results – Created datasets

Power system case	Boundary $N_2 = 10^4$	Inside (MVND) $N_3 = 10^5$	Overall Secure	Overall Points
AC-OPF without N-1 security and without uncertainty				
<i>case3_lmbd</i>	69.5%	36.5%	40.6%	114'389
<i>case5_pjm</i>	68.6%	69.4%	69.3%	125'432
<i>case14_ieee</i>	73.3%	59.0%	61.0%	147'047
<i>case24_ieee_rts</i>	66.8%	44.3%	48.7%	131'158
<i>case30_ieee</i>	75.0%	50.2%	54.0%	124'944
<i>case39_epri</i>	57.2%	29.9%	33.9%	154'635
<i>case57_ieee</i>	58.9%	35.2%	38.9%	150'865
<i>case73_ieee_rts</i>	63.9%	51.1%	52.7%	222'730
<i>case118_ieee</i>	53.2%	47.0%	47.6%	209'996
<i>case162_ieee_dtc</i>	50.0%	40.1%	41.7%	129'165
<i>case200_tamu</i>	50.2%	36.6%	38.1%	177'023
<i>case300_ieee</i>	50.0%	32.6%	34.7%	163'087
<i>case500_tamu</i>	50.0%	35.4%	37.1%	174'774

Accuracy of neural network classifiers

using the created datasets

case	full dataset	only boundary
AC-OPF without N-1 security and without uncertainty		
<i>case14_ieee</i>	78.2%	60.5%
<i>case39_epri</i>	74.6%	38.5%
<i>case162_ieee_dtc</i>	84.4%	49.8%
AC-OPF including N-1 security and uncertainty		
<i>case39_epri</i>	81.0%	80.4%
<i>case162_ieee_dtc</i>	93.4%	31.9%