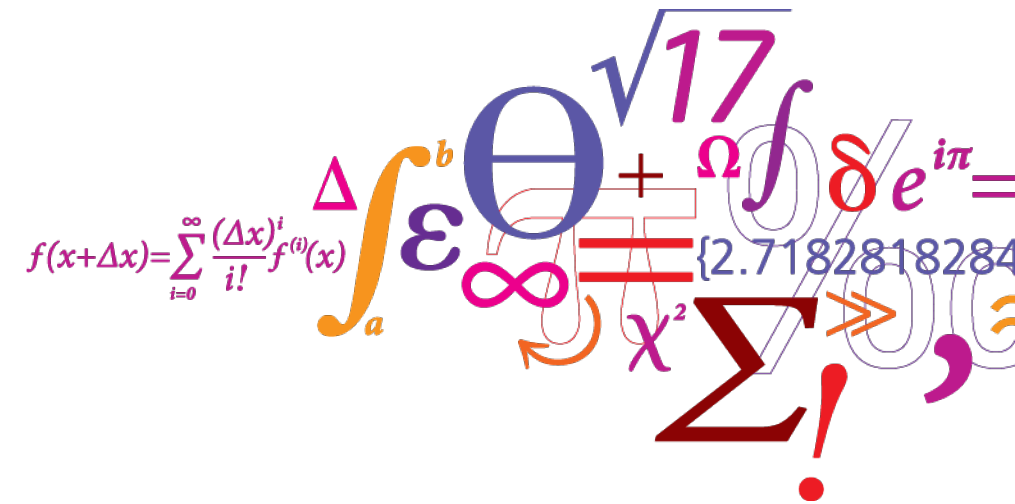
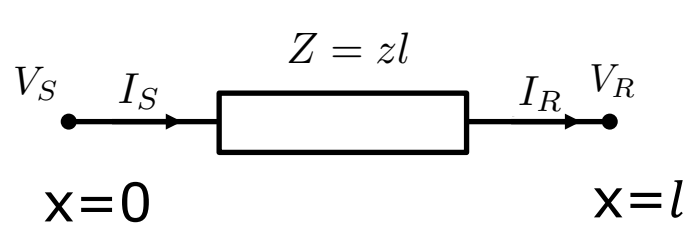


Transmission Lines

Spyros Chatzivasileiadis

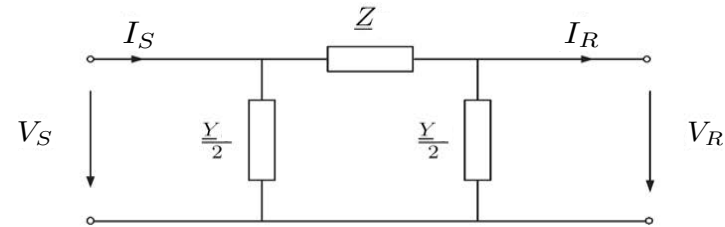


Summary from last time



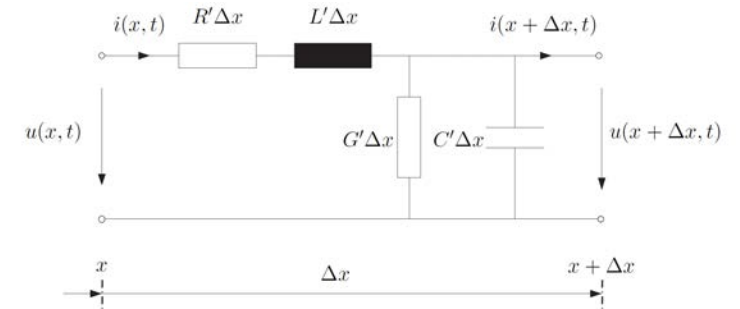
$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} 1 & Z \\ 0 & 1 \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

←
 $Y = 0$



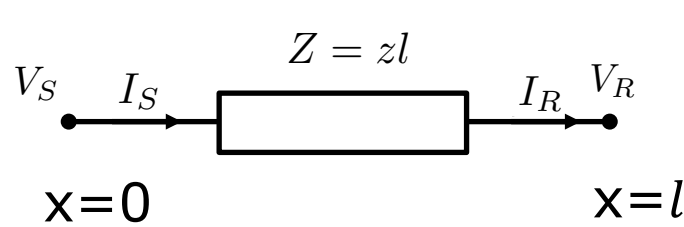
$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z \\ Y \left(1 + \frac{YZ}{4} \right) & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

←
 $\gamma l \ll 1$



$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} \cosh(\gamma l) & Z_c \sinh(\gamma l) \\ \frac{1}{Z_c} \sinh(\gamma l) & \cosh(\gamma l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

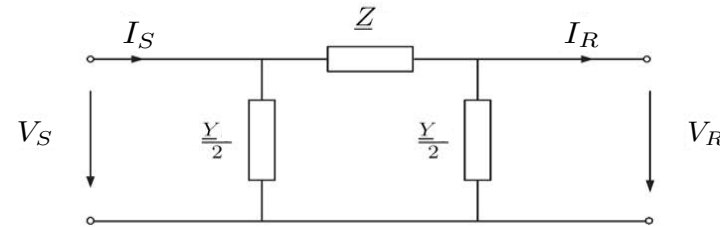
Summary from last time



$l \leq 25 \text{ km}$

$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} 1 & Z \\ 0 & 1 \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

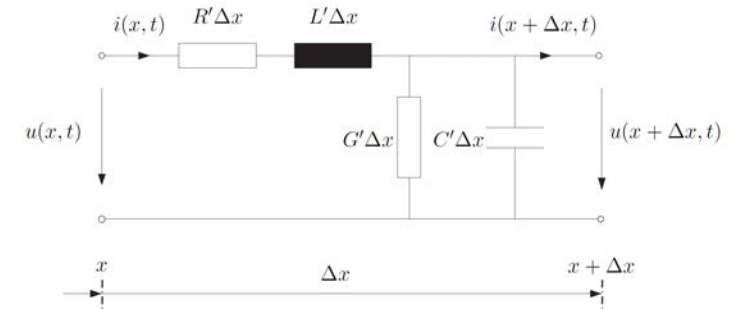
$Y = 0$



$l \leq 250 \text{ km}$

$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} 1 + \frac{YZ}{2} & Z \\ Y \left(1 + \frac{YZ}{4} \right) & 1 + \frac{YZ}{2} \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

$\gamma l \ll 1$



$l > 250 \text{ km}$

$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} \cosh(\gamma l) & Z_c \sinh(\gamma l) \\ \frac{1}{Z_c} \sinh(\gamma l) & \cosh(\gamma l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

Questions from last time

- What is the meaning of γl ?
 - It has to do with the propagation of the voltage wave. Even if no impedance is assumed the voltage is a traveling wave and as a result at one point x_1 it is going to be different from a voltage at another point x_2
 - The Ferranti effect has to do with these changes of voltage in space

Goals for Today

- Lossless line
- Surge impedance
- Surge impedance loading
- Voltage profiles
- Steady-state stability limit
- Maximum Power Flow
- Line Loadability

Surge impedance and propagation constant for lossless lines

$$z = R' + j\omega L' \quad \Omega/m$$

$$y = G' + j\omega C' \quad S/m$$

• For lossless lines

$$-R' = 0$$

$$-G' = 0$$

$$Z_c = \sqrt{\frac{z}{y}}$$

$$\gamma = \sqrt{zy}$$

1. How much is Z_c and γ ?

2. How much are the ABCD parameters?

$$\sinh(y) = \frac{e^y - e^{-y}}{2}$$

$$\cosh(y) = \frac{e^y + e^{-y}}{2}$$

$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} \cosh(\gamma l) & Z_c \sinh(\gamma l) \\ \frac{1}{Z_c} \sinh(\gamma l) & \cosh(\gamma l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

ABCD Parameters

$$\begin{bmatrix} V_S \\ I_S \end{bmatrix} = \begin{bmatrix} \cos(\beta l) & Z_c \sin(\beta l) \\ \frac{1}{Z_c} \sin(\beta l) & \cos(\beta l) \end{bmatrix} \begin{bmatrix} V_R \\ I_R \end{bmatrix}$$

- For a **lossless** line:
 - The surge impedance is pure resistive
 - The propagation constant is pure imaginary

- For $\beta l < \pi$, the equivalent π -circuit is also lossless
 - $\beta l < \pi$: for $l < 3000$ km for 50 Hz

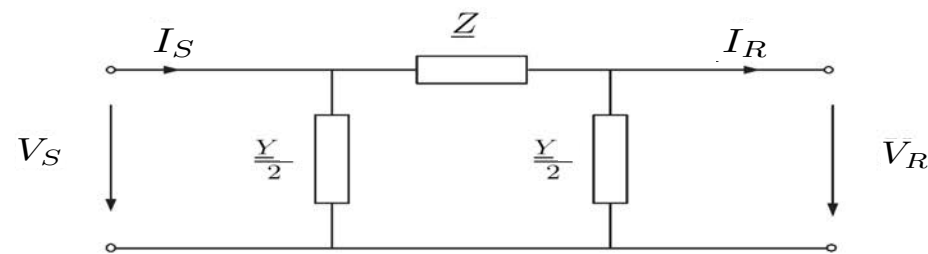


Figure 5.26. Π equivalent circuit diagram of a homogenous power line.

Wavelength

- Wavelength: distance required to change the phase of voltage or current by 2π

$$V(x) = \cos(\beta x)V_R + jZ_c \sin(\beta x)I_R$$

$$I(x) = \frac{j \sin(\beta x)}{Z_c}V_R + \cos(\beta x)I_R$$

$$\lambda = \frac{2\pi}{\beta}$$

$$f\lambda = \frac{1}{\sqrt{LC}}$$

- Velocity of propagation of voltage and current along a lossless line
- For overhead lines it is equal to the light speed, i.e. $3 \cdot 10^8$ m/s

How much is λ ?

Wavelength

- Wavelength: distance required to change the phase of voltage or current by 2π

$$V(x) = \cos(\beta x)V_R + jZ_c \sin(\beta x)I_R$$

$$I(x) = \frac{j \sin(\beta x)}{Z_c}V_R + \cos(\beta x)I_R$$

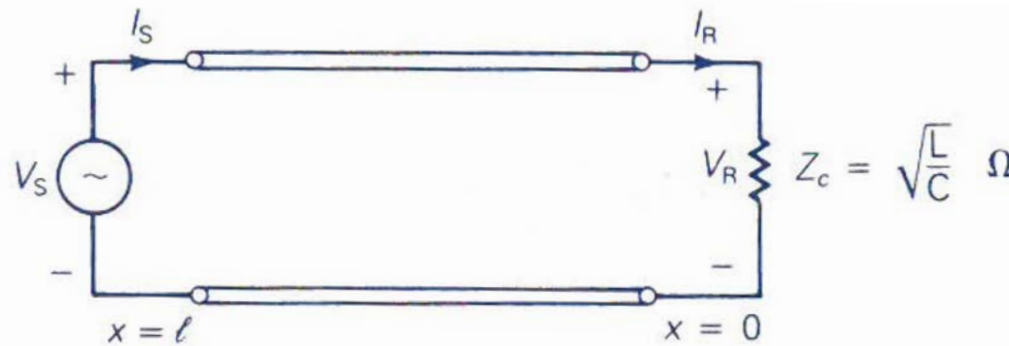
$$\lambda = \frac{2\pi}{\beta} \quad f\lambda = \frac{1}{\sqrt{LC}}$$

$$\lambda = 6000 \text{ km for } 50 \text{ Hz}$$

Surge Impedance

FIGURE 5.9

Lossless line terminated by its surge impedance



How much is

1. $V(x)$?
2. $I(x)$?
3. $S(x)$?

$$I_R = \frac{V_R}{Z_c}$$

Voltage Profiles

FIGURE 5.10

Voltage profiles of an uncompensated lossless line with fixed sending-end voltage for line lengths up to a quarter wavelength

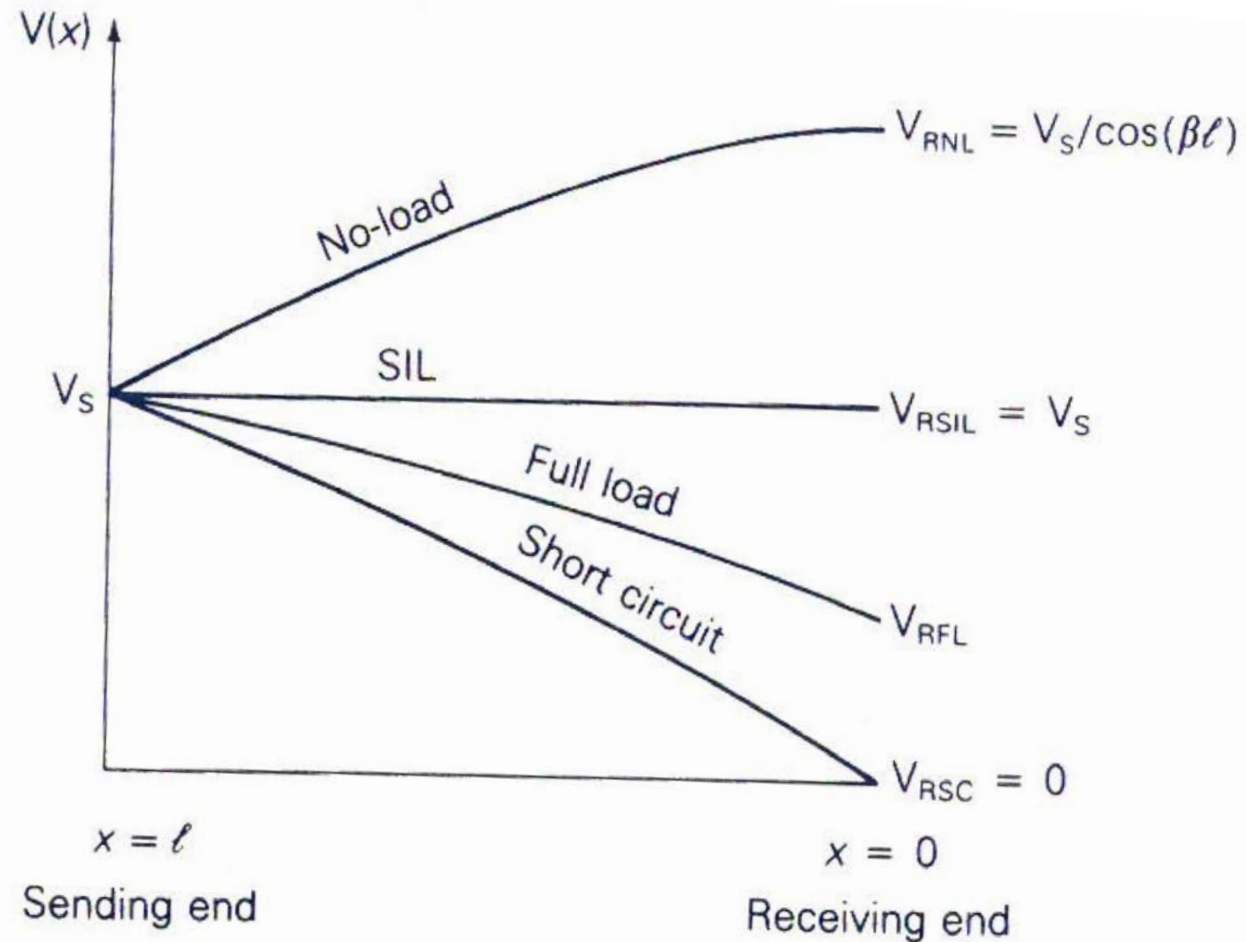


Figure taken from:
J. Glover, T. Overbye, M. Sarma, Power System Analysis and Design, Cengage Learning, Sixth Edition, 2016

Steady-state stability limit

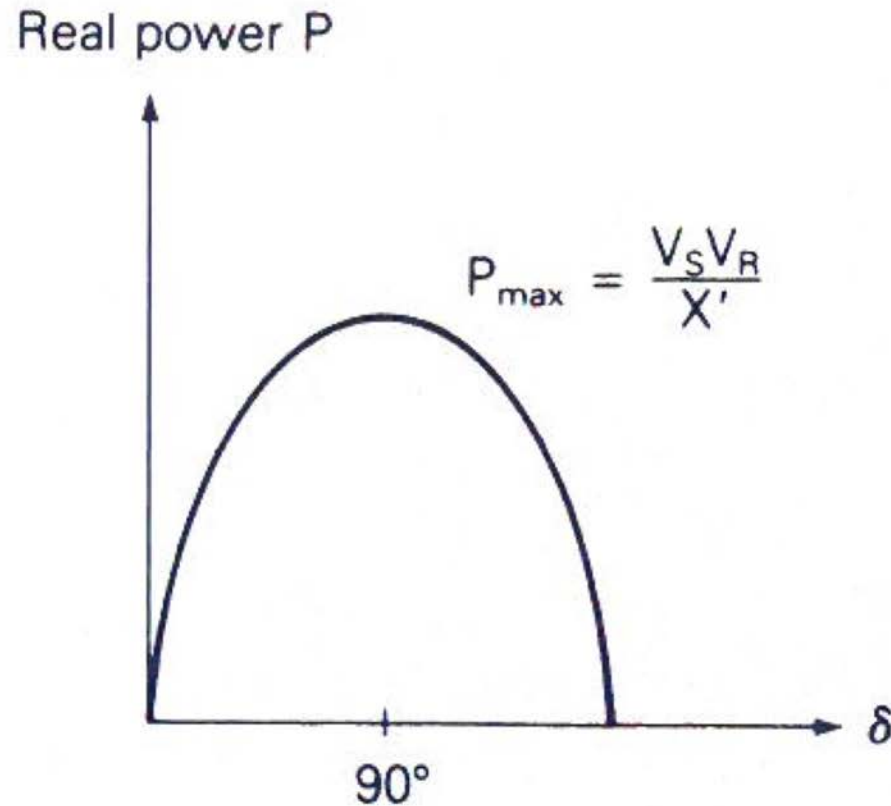


FIGURE 5.11

Real power delivered by a lossless line versus voltage angle across the line

Line Loadability

FIGURE 5.12

Transmission-line loadability curve for 60-Hz overhead lines—no series or shunt compensation

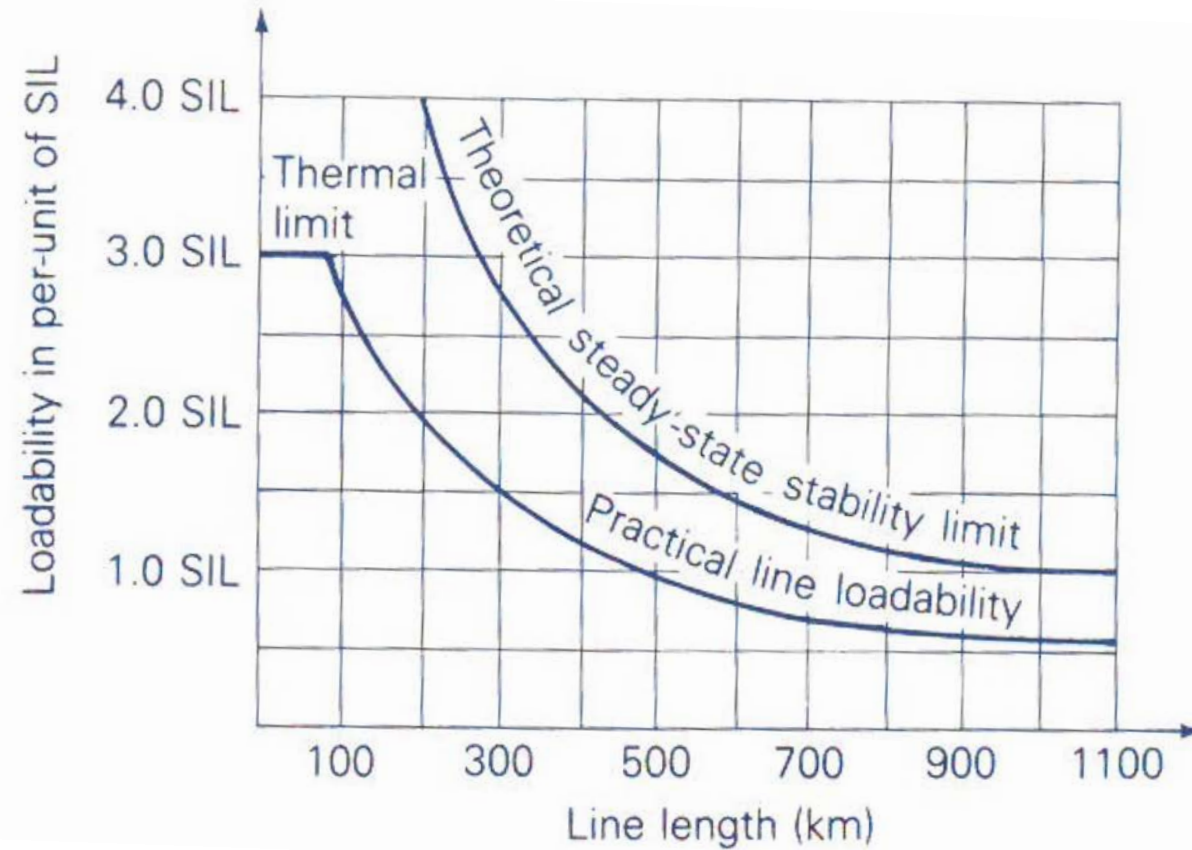


Figure taken from:
J. Glover, T. Overbye, M. Sarma, Power System Analysis and Design, Cengage Learning, Sixth Edition, 2016

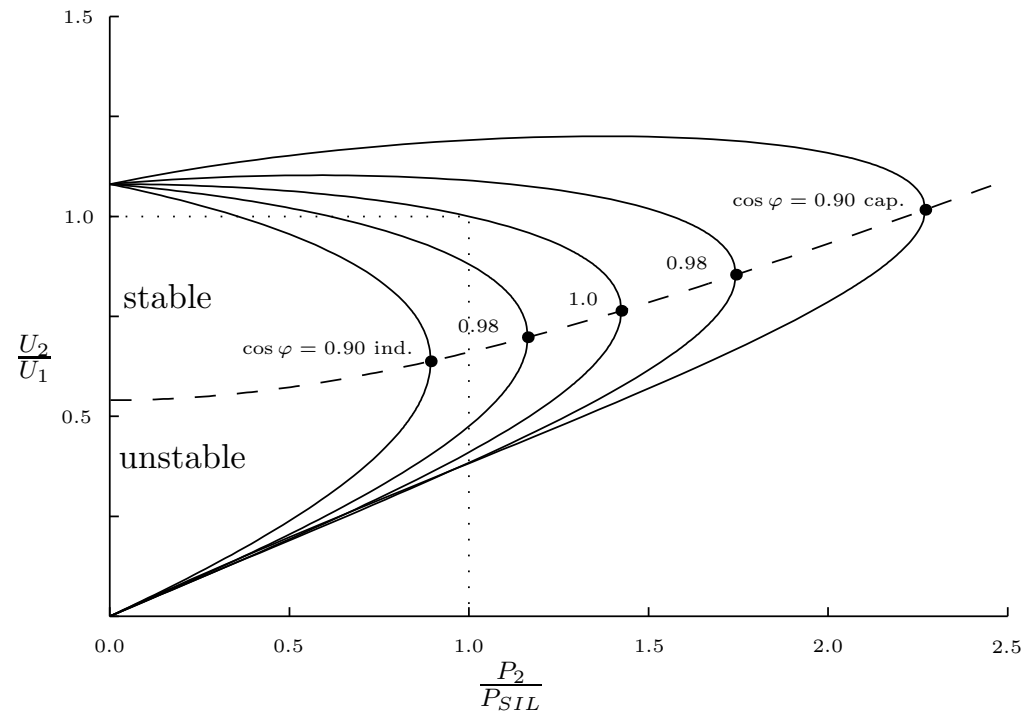


Figure 6.10. Voltage at the end of the line as a function of the delivered active power for different line loadings. U_1 is kept constant at 1.0 pu.

Figure taken from:
 G. Andersson and C. Franck, *Electric Power Systems, Lecture Notes, ETH Zurich, 2013*